# 11 Advanced Concepts of Discrete-Choice Theory

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- 11.4 [Advanced II: How to Assess Reliability (German script)]

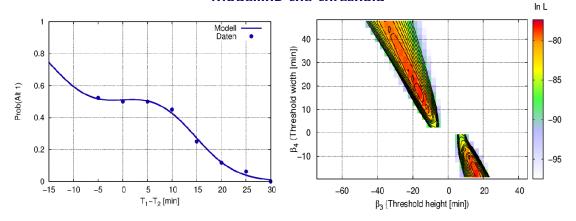


# Parameter Nonlinear Models

Application: Determining subjective thresholds/indifference regions

Person class	Time Alternative 1 [min]	Time Alternative 2 [min]	Choice Alt. 1	Choice Alt. 2
1	25	30	11	10
2	30	30	10	10
3	35	30	10	10
4	40	30	9	11
5	45	30	5	15
6	50	30	2	15
7	55	30	1	15
8	60	30	0	15

### Modelling the threshold

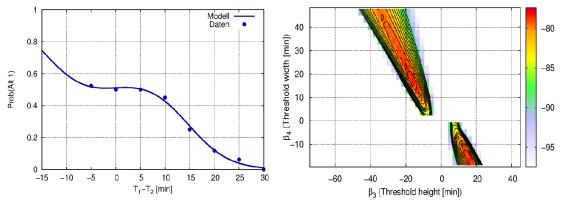


$$V_{n1} - V_{n2} = \beta_1 + \beta_2 \left[ \Delta T_n + \beta_3 \tanh\left(\frac{\Delta T_n}{\beta_4}\right) \right]$$

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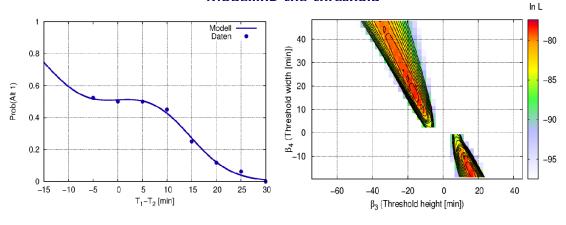


$$V_{n1} - V_{n2} = \beta_1 + \beta_2 \left[ \Delta T_n + \beta_3 \tanh\left(\frac{\Delta T_n}{\beta_4}\right) \right]$$
$$\hat{\beta}_1 = 0.043 \pm 0.236 \text{ AC}$$

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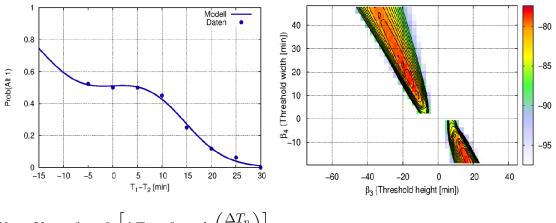


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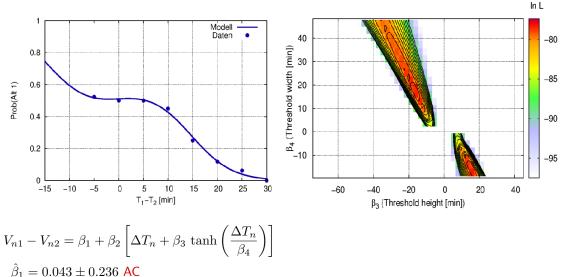
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$$\begin{split} V_{n1} - V_{n2} &= \beta_1 + \beta_2 \left[ \Delta T_n + \beta_3 \tanh\left(\frac{\Delta T_n}{\beta_4}\right) \right] \\ \hat{\beta}_1 &= 0.043 \pm 0.236 \text{ AC} \\ \hat{\beta}_2 &= -0.29 \pm 0.38 \text{ asymptotic time sensitivity} \\ \hat{\beta}_3 &= -15 \pm 18 \text{ degree of nonlinearity} \geq -\beta_4 \end{split}$$

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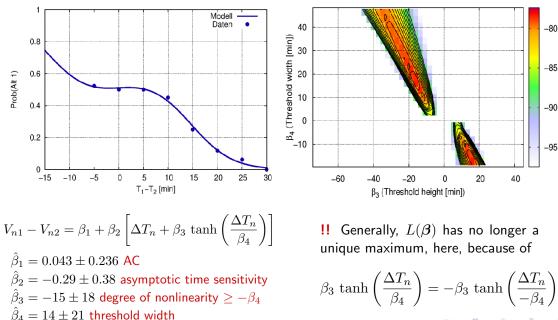
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 $\hat{\beta}_1 = 0.043 \pm 0.230$  AC  $\hat{\beta}_2 = -0.29 \pm 0.38$  asymptotic time sensitivity  $\hat{\beta}_3 = -15 \pm 18$  degree of nonlinearity  $\geq -\beta_4$  $\hat{\beta}_4 = 14 \pm 21$  threshold width

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#### Modelling the threshold

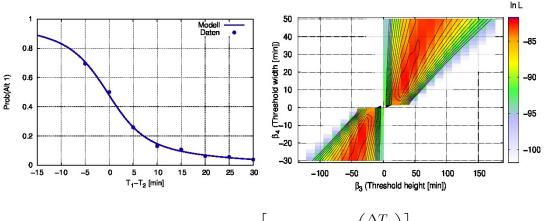


#### The reverse: Increased sensitivity at reference point

Person class	Time Alternative 1 [min]	Time Alternative 2 [min]	Choice Alt. 1	Choice Alt. 2
1	25	30	16	7
2	30	30	10	10
3	35	30	7	20
4	40	30	3	20
5	45	30	3	25
6	50	30	2	30
7	55	30	1	17
8	60	30	2	50

Such increased sensitivity at the reference (here: equal trip times) is proposed by the **Prospect Theory** of Kahneman/Twersky in certain situations

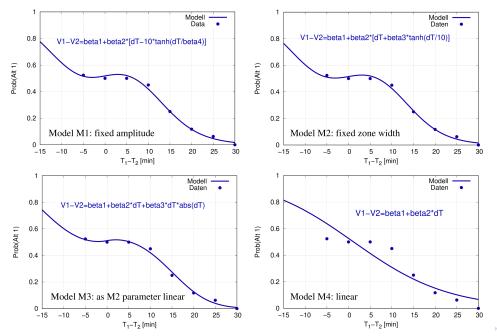
# Modelling the increased sensitivity



$$V_{n1} - V_{n2} = \beta_1 + \beta_2 \left[ \Delta T_n + \beta_3 \tanh\left(\frac{\Delta T_n}{\beta_4}\right) \right]$$
$$\hat{\beta}_1 = -0.08 \pm 0.25,$$
$$\hat{\beta}_2 = -0.05 \pm 0.10,$$
$$\hat{\beta}_3 = 27 \pm 101,$$
$$\hat{\beta}_4 = 10 \pm 16$$

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#### Four further models applied to the threshold data



#### Motivation

When taking decisions, the available options are often coupled in a way that i.i.d. random utilities are not applicable:

### Destination and mode choice

Destination city and job offers when about to moving

Expansion of a company: Creating a new branch office and if so, where?

In these cases, a decision involves taking two or more sub-decisions with nearly fixed random utilities in the associated alternative sets, so the total random utility is correlated

#### ⇒ **Red-Bus-Blue-Bus** problem.

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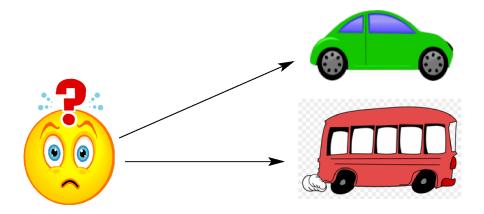
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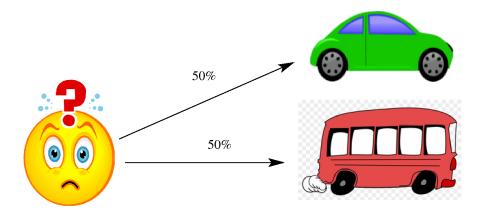


Times and costs equal, AC zero

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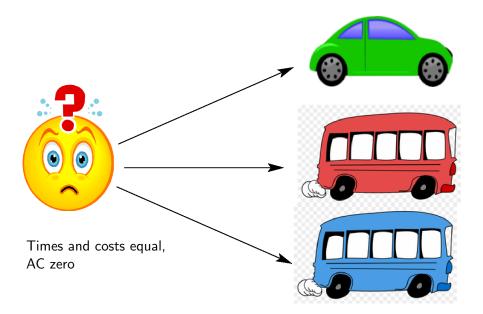
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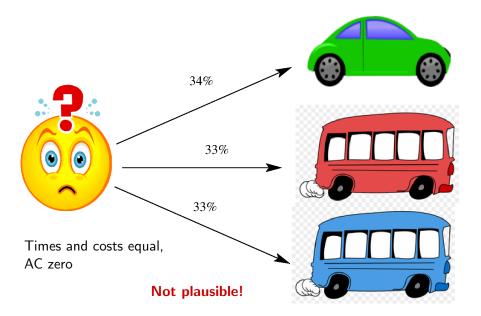


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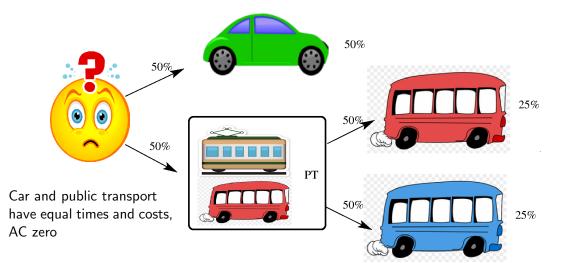
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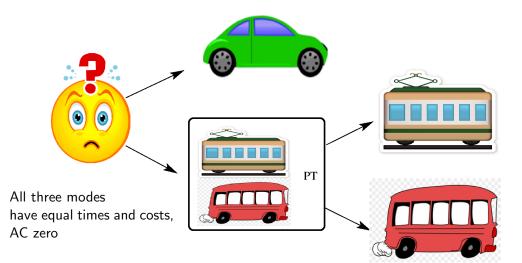


### 100% correlated random utilities: Problem solved!

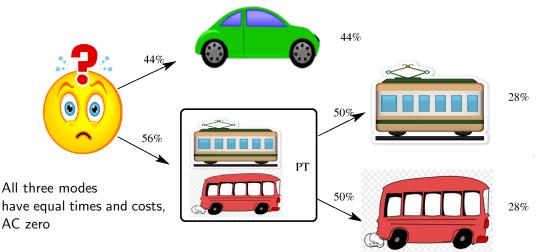


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### Nontrivial nested decision: partial correlations



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Average PT utiliy higher than that of bus or tram alone because some prefer tram, some bus

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# The general GEV generating function

All the GEV models are defined via a Generating function  $G(y) = G(y_1, ..., y_I)$  satisfying following formal conditions:

• Not negative:  $G(\boldsymbol{y}) \ge 0$  for all  $\boldsymbol{y}$ ,

• Asymptotics:  $G \to \infty$  if any  $y_i \to \infty$ ,

Sign of derivatives:

$$\begin{array}{rcl} G_i &\equiv& \displaystyle \frac{\partial G}{\partial y_i} \geq 0, \\ \\ G_{ij} &\equiv& \displaystyle \frac{\partial^2 G}{\partial y_i \ \partial y_j} \leq 0 \ \text{if} \ i \neq j, \\ \\ G_{ijk} &\geq& 0 \ \text{and so on}, \end{array}$$

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# The Nobel-Price winning result of McFadden et. al.

Any GEV function  $G(\boldsymbol{y})$  satisfying the above four conditions

• generates a random vector  $\epsilon$  satisfying a generalized extreme-value distribution with the distribution function

 $F(\boldsymbol{e})=P(\epsilon_1\leq e_1,...,\epsilon_I\leq e_I)=e^{-G(\boldsymbol{y})}$  with  $y_i=e^{-e_i}$ 

▶ has analytic choice probabilities when maximizing the total utilities  $U_i = V_i + \epsilon_i$ :

$$P_i = rac{y_i G_i(m{y})}{G(m{y})}$$
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- ! Because a distribution function  $F = e^{-G}$  must be  $\leq 1$  (the condition  $F \geq 0$  is satisfied automatically)
- ? Why  $G \to \infty$  if any  $y_i \to \infty$ ?
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### Question: Check the conditions for G(y)

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Generating function:

$$G(\boldsymbol{y})^{\mathsf{MNL}} = \sum_{j=1}^{I} y_j$$

Distribution function of the random utilities (RUs):

$$F(e) = \exp\left[-G\left(e^{-e_1},\ldots\right)\right] = \exp\left(-\sum_j e^{-e_j}\right)$$
$$= \prod_j \exp\left(-e^{-e_j}\right) \Rightarrow \epsilon_i \sim \text{ i.i.d. Gumbel}$$

Choice probabilities:

$$G_i = \frac{\partial G}{\partial y_i} = 1,$$
  

$$P_i = \frac{y_i}{\sum_{j=1}^I y_j} = \frac{\exp(V_i)}{\sum_{j=1}^I \exp(V_j)}$$

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# Special Case I: Multinomial-Logit

Generating function:

$$G(\boldsymbol{y})^{\mathsf{MNL}} = \sum_{j=1}^{I} y_j$$

Distribution function of the random utilities (RUs):

$$F(e) = \exp\left[-G\left(e^{-e_1},\ldots\right)\right] = \exp\left(-\sum_j e^{-e_j}\right)$$
$$= \prod_j \exp\left(-e^{-e_j}\right) \Rightarrow \epsilon_i \sim \text{ i.i.d. Gumbel}$$

Choice probabilities:

$$G_i = \frac{\partial G}{\partial y_i} = 1,$$
  

$$P_i = \frac{y_i}{\sum_{j=1}^I y_j} = \frac{\exp(V_i)}{\sum_{j=1}^I \exp(V_j)}$$

- ▶ Hierarchical decision: i = (l, m), l: top-level alternatives, m second-level alternatives depending on l
- Generating GEV function:

$$G^{\mathsf{NL}}(\boldsymbol{y}) = \sum_{l=1}^{L} \left(\sum_{m=1}^{M_l} y_{lm}^{1/\lambda_l}\right)^{\lambda_l}$$

where  $\lambda_l \in [0,1]$  determine the correlations of the RUs in "nest" l:

- ▶  $\lambda_l \rightarrow 1$ : Limit of MNL, zero correlation  $\Rightarrow$  check it!
- $\blacktriangleright\ \lambda_l \to 0:$  no RUs inside the nests, correlation=1: sequential model: blue and red buses
- Distribution of the RUs:

$$\begin{split} F(e) &= \exp\left[-\sum_{l}\left(\sum_{m}e^{-e_{lm}/\lambda_{l}}\right)^{\lambda_{l}}\right] = \prod_{l}\exp\left[-\left(\sum_{m}e^{-e_{lm}/\lambda_{l}}\right)^{\lambda_{l}}\right] \\ &= \prod_{l}F_{l}(e_{l}) \Rightarrow \text{ independent at top level} \end{split}$$

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### Nested Logit choice probabilities

Insert  $G^{NL}(\boldsymbol{y})$  into the general expression  $P_i = y_i G_i/G$ :

$$P_{i} = P_{lm} = P_{l}P_{m|l} = \frac{e^{V_{lm}/\lambda_{l}} \left(\sum_{m'} e^{V_{lm'}/\lambda_{l}}\right)^{\lambda_{l}-1}}{\sum_{l'} \left(\sum_{m'} e^{V_{l'm'}/\lambda_{l'}}\right)^{\lambda_{l'}}}$$

 $\Rightarrow$  complicated and non-intuitive!

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- Set/assume  $V_{lm} = W_l + \tilde{V}_{lm}$ 
  - $W_l$ : top-level contributions not appearing inside the nests
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- Then, the NL choice probabilities can be formulated as

$$P_{lm} = P_l P_{m|l}, \quad P_l = \frac{e^{W_l + \lambda_l I_l}}{\sum_{l'} e^{W_{l'} + \lambda_{l'} I_{l'}}}, \quad P_{m|l} = \frac{e^{\tilde{V}_{lm}/\lambda_l}}{\sum_{m'} e^{\tilde{V}_{lm'}/\lambda_l}}$$

with the inclusion values

$$I_l = \ln\left(\sum_m e^{ ilde{V}_{lm}/\lambda_l}
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(calibrate first  $e^{V_{lm}/\lambda_l}$ , then determine  $\lambda_l$  with fixed  $I_l$  in the outer MNL calibration)

- ? Argue that the outer nest decision is a normal MNL with the *effective nest utilities* given by  $\lambda_l I_l$ . Because for these assumptions  $P_l$  has the normal MNL form
- 7 Show that  $\lambda_l I_l$  is at least as high as the utility  $V_{lm_l^*}$  of the best alternative within the nest and that  $\lambda_l I_l = \tilde{V}_{lm_l^*}$  for  $\lambda_l \to 0$ . All contributions of the sum inside the log are exponentials and thus positive. Furthermore, the In function is strictly monotonously increasing. Hence,  $\lambda_l I_l$  is larger than any single  $\tilde{V}_{lm}$  including the maximum. For  $\lambda_l \to 0$ , only the maximum contributes to the sum
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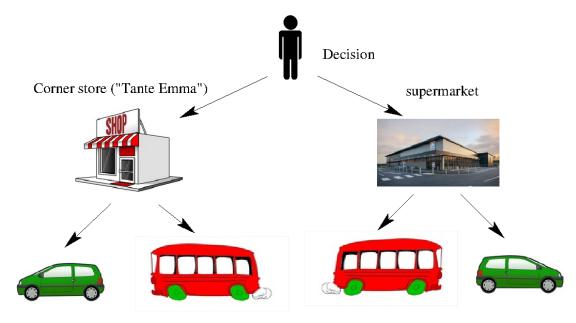
$$P_{lm} = P_l P_{m|l}, \quad P_l = \frac{e^{W_l + \lambda_l I_l}}{\sum_{l'} e^{W_{l'} + \lambda_{l'} I_{l'}}}, \quad P_{m|l} = \frac{e^{\tilde{V}_{lm}/\lambda_l}}{\sum_{m'} e^{\tilde{V}_{lm'}/\lambda_l}}$$

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### 11.2.3 Example: Combined Destination and Mode Choice

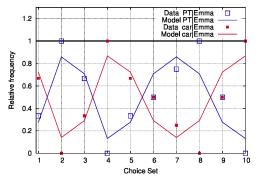


### Combined destination and mode choice: the data

Per- son group	T [min] Emma, PT	T [min] Emma, car	T [min] superm, PT	T [min] superm, car	Fridge fill level F	$y_{11}$	$y_{12}$	$y_{21}$	$y_{22}$
1	25	15	25	20	0.9	1	2	0	0
2	25	30	40	30	0.8	3	0	0	1
3	20	20	30	30	0.7	2	1	1	1
4	25	10	25	10	0.6	0	3	0	2
5	15	5	30	20	0.5	1	2	0	2
6	15	15	25	20	0.4	1	1	0	1
7	15	20	45	45	0.3	3	1	0	1
8	15	15	15	15	0.2	1	0	2	3
9	25	15	40	30	0.1	1	1	0	1
10	25	10	25	20	0.0	0	1	1	3

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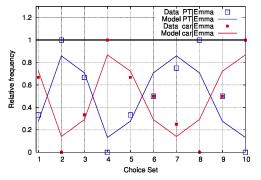
### **Conditional modal splits**



Observed and modelled modal split when driving to "Aunt Emma"

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## **Conditional modal splits**

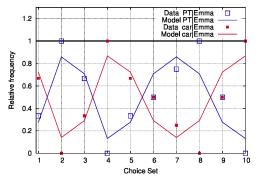


Observed and modelled modal split when driving to "Aunt Emma"

$$P_{m|n1} = \frac{\exp(\tilde{V}_{n1m}/\lambda_1)}{\sum_{m'}\exp(\tilde{V}_{n1m'}/\lambda_1)},$$
  
$$\tilde{V}_{n1m}/\lambda_1 = \beta_1 T_{n1m} + \beta_2 \delta_{m1},$$
  
$$\hat{\beta}_1 = -0.18, \ \hat{\beta}_2 = +0.88$$

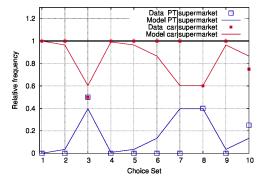
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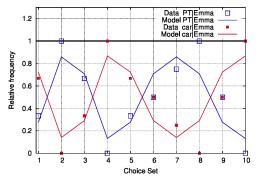
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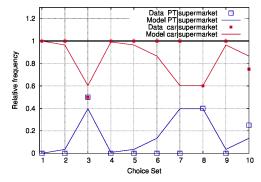
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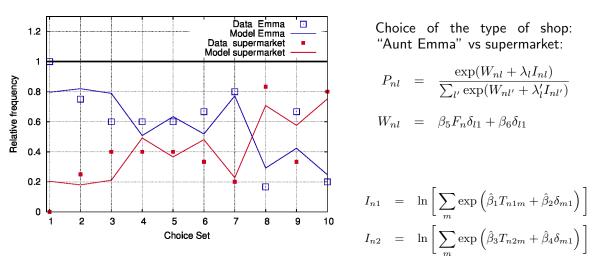


Observed and modelled modal split when driving to the supermarket

$$P_{m|n2} = \frac{\exp(\tilde{V}_{n2m}/\lambda_2)}{\sum_{m'} \exp(\tilde{V}_{n2m'}/\lambda_2)},$$
  
$$\tilde{V}_{n2m}/\lambda_2 = \beta_3 T_{n2m} + \beta_4 \delta_{m1},$$
  
$$\hat{\beta}_3 = -0.29, \ \hat{\beta}_4 = -0.42$$

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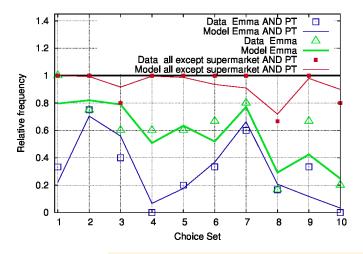
#### Top-level choice of the type of shop



 $\hat{\beta}_5 = 2.9, \ \hat{\beta}_6 = -2.0, \ \hat{\lambda}_1 = 0.17, \ \hat{\lambda}_2 = 0.21.$ 

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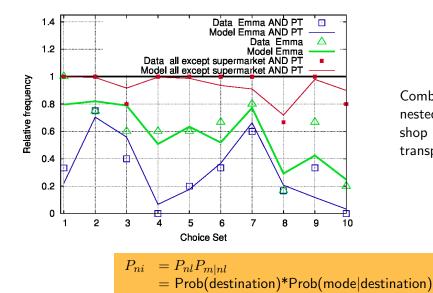
### Final combined probabilities



Combined nested choice of shop type and transport mode

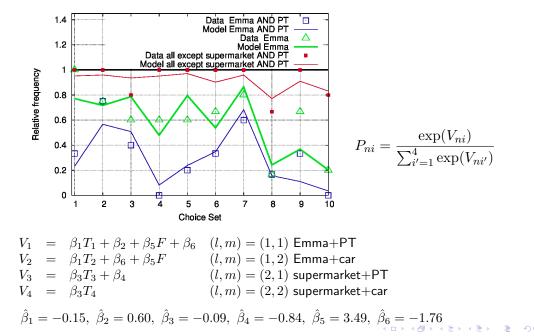
 $P_{ni} = P_{nl}P_{m|nl}$ = Prob(destination)\*Prob(mode|destination)

#### **Final combined probabilities**



Combined nested choice of shop type and transport mode

#### **Counter check: normal MNL**



### **11.3 Advanced I: Mixed-Logit Models**

if time allows, see German script, Sec. 4.14

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